Developing Improved Greedy Crossover to Solve Symmetric Traveling Salesman Problem

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Abstract

The Traveling Salesman Problem (TSP) is one of the most famous optimization problems. Greedy crossover designed by Greffenstette et al, can be used while Symmetric TSP (STSP) is resolved by Genetic Algorithm (GA). Researchers have proposed several versions of greedy crossover. Here we propose improved version of it. We compare our greedy crossover with some of recent crossovers, we use our greedy crossover and some recent crossovers in GA then compare crossovers on speed and accuracy.

Keywords: Greedy Crossover, Genetic Algorithm, Traveling Salesman Problem.

1. Introduction

After introducing Genetic Algorithm (GA) by Holand [1] many GA crossover operators have been invented by researchers because the performance of GA depends on an ability of these operators. PMX [1] is one of first crossovers proposed by Goldberg and Lingle in 1985. Reference [14] stated some important shortcomings of PMX and to overcome them proposed extended PMX (EPMX). DPX [10] [11] is another crossover that produces child with greedy reconnect of common edges in two parents. Greedy Subtour Crossovers (GSXs) [7] [8] [9] family are another groups of crossovers that operate fast. GSX-2 [8] is improved version of GSX-0 [6] and GSX-1 [7].

In this paper we propose our Improved GX (IGX). We use IGX and some recent crossovers in GA to solve some TSPLIB's problems then we compare these crossovers on speed and accuracy. So rest of this paper organized as follows: In following section we represent some versions of GX. In section 3 we propose IGX. We represent GA in section 4. We put forward our experimental results in section 5 and summarize paper in 6.

2. Greedy Crossover (GX)

Major GXs select a node and copy it to child then it probes witch of its neighbors is nearest to it, so the nearest

one is copied to child and this process is continued until child tour be completed. We show some previous versions of GX by example in Fig 2. In this example we use a graph with 8 nodes that its edges cost are as distance matrix in Fig 1.

	1	2	3	4	5	6	7	8
1	0	12	19	31	22	17	23	12
2	12	0	15	37	21	28	35	22
3	19	15	0	50	36	35	35	21
4	31	37	50	0	20	21	37	38
5	22	21	36	20	0	25	40	33
6	17	28	35	21	25	0	16	18
7	23	35	35	37	40	16	0	14
8	12	22	21	38	33	18	14	0

Fig. 1 Distance matrix

VGX operates more accurate than other versions but it is slow. Our purpose is to design new version of GX not only has more accurate but also operates fast.

3. Improved Greedy Crossover (IGX)

Previous versions of GX were slow or had not enough accuracy so we designed improved version of GX and named it improved greedy crossover (IGX). IGX is same to other versions of GX but in each step it probes only nodes that are not in child tour. To achieve this purpose we use two auxiliary double-linked list that each of them present one of parents tour. When a node is selected and copied to child tour it is eliminated from both double-liked lists. We show IGX in Fig.3. It can be easily seen that time complexity of IGX is O(n). It needs O(n) to form double-linked list and O(n) to complete child. Please consider that to complete child tour IGX need <u>n</u> steps and in each step it probes 4 nodes.

4. Genetic Algorithm (GA)

To compare crossovers we use each of them in GA to solve some of TSPLIB data set then we compare speed and accuracy of them. We define GA as below:



- 1) Initialize population with random tours
- 2) while population is changed
- 3) *for* i =1 to Generation-Size
- 4) Select father and mother from population
- 5) child \leftarrow operate one of crossovers
- 6) operate 2_Opt_move_based LS on child [14]
- 7) operate 3_Opt_move_based LS on child [14]
- 8) add child to population
- 9) reduce population

10) return best individual of population

GA use random tours to initialize population in line 1. After that child is produced in line 5, it is improved by 2opt and 3-opt and then it is added to population. Low quality tours are eliminated from population in line 9. "while" loop in line 2 repeated until no better child produced. If one of produced children is better than one of population individual then "while" loop will be continued.

father 4 5 7 3 2 1 6 8 i<	Special cases father 4 5 7 3 2 1 6 8 mother: 5 1 7 3 6 2 4 8 3, 1, 6 and 4 are neighbors of 2 and 1 are closer to it but 1 is already exist in child then we cannot copy it to child.			
child 1 step 2: father 4 5 7 3 2 1 6 8 mother: 5 1 7 3 6 2 4 8 In each step four neighbors of recent selected node are considered and which is closer to it is selected. 2, 6, 5 and 7 are neighbors of 1 and 2 is closer to it so is copied to child. child 1 2 1 <t< td=""><td colspan="4">Reference [6] operates very greedy and selects closer</td></t<>	Reference [6] operates very greedy and selects closer			

Fig. 2 GXs review

5. Experiments and Results

We implemented all of algorithms with c# language and used .NET 2008 and ran all experiments on AMD Dual Core 2.6 GHZ. We used each of EPMX[14], GSX-2 [7], UHX¹ [15], VGX [6], DPX [10][11], PBX [12] and our IGX in GA to solve eil51, eil101, kroA100, kroA200, a280 and lin318 instances which are all from TSPLIB [17]. We ran GA with each of seven crossovers for thirty times. In all of these runs we set Population-Size=50 and Generation-Size=500. Table I shows our comparison results. In this table "Best length", "Average length" and "Worst length" show the best, average, and worst tour lengths respectively. "Number of repeat "while" loop in lines 2 to 9" column points out how many times lines 2 to 9 in Fig. 4 is executed also "Average Time" column gives the average running time in seconds. In "Best length", "Average length" and "Worst length" columns the values in parentheses is result of calculating



¹. This crossover is unnamed and operates heuristically so we name it Unnamed Heuristic crossover (UHX).

cost of solution found - known optimum cost known optimum cost

These results show that IGX has more accuracy than other six crossovers. Sixth column in table I shows that GSX-2 and EPMX have more average number of repeat "while" loop in lines 2 to 8 than other crossovers it means that they have high diversity and can produce many different tours also in attention to this column we can result that they are quick.

Fig.4 summarize fourth column of table 1 and show average length of tours obtained by GA when uses each of crossovers. Fig.5 outline last column of table 1 and show average time of GA when uses each of crossovers.

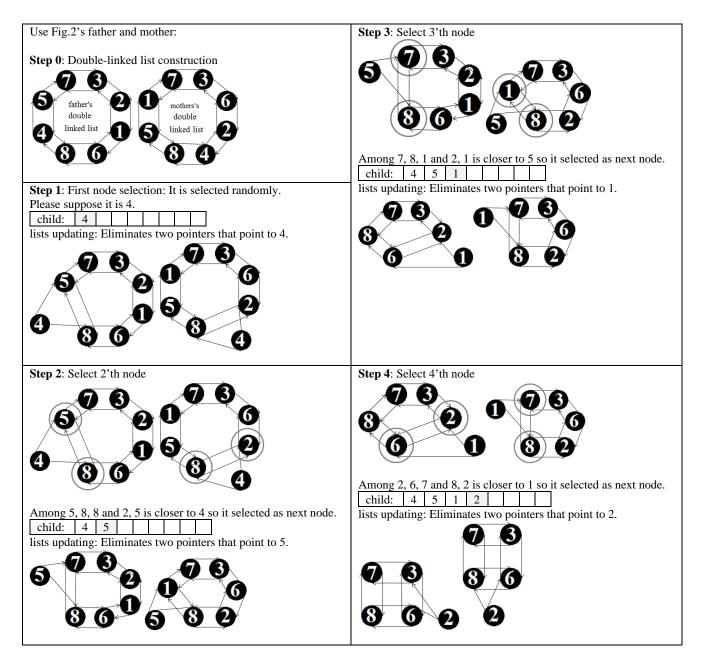


Figure 3: IGX

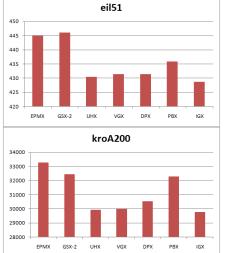


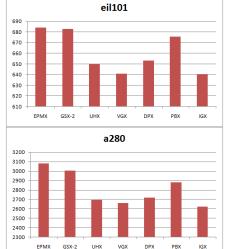
Greedy crossover (GX) designed by Greffenstette et al, is one of first heuristic crossover that can be used while Symmetric TSP (STSP) is resolved by Genetic Algorithm(GA). To improve its performance researchers have presented some versions of it but all of them are slow or has not enough accurate. In this paper we proposed new versions of it. IGX has more accuracy than not only any versions of GXs but any other considered crossover in this paper. In experiments we used IGX and six other recent crossovers in our GA to solve TSP instances. Experimental results have shown that when GA uses IGX has more accuracy than when uses other crossovers and also IGX is quick and complexity time of it is O(n).

Problem	Crossover	Best length	Average length	Worst length	Number of repeat "while"	Average
name	name	(quality)	(quality)	(quality)	loop in lines 2 to 8	Time(second)
Eil51	EPMX	433(1.64%)	445(4.46%)	459(7.75%)	53	3.43044
	GSX2	428(0.47%)	446.1(4.72%)	468(9.86%)	42	1.56
	UHX	426(0%)	430.5(1.06%)	438(2.82%)	29	5.31492
	VGX	430(0.94%)	431.5(1.29%)	434(1.88%)	24	4.23228
	DPX	429(0.7%)	431.5(1.29%)	434(1.88%)	21	1.51632
	PBX	429(0.7%)	435.9(2.32%)	445(4.46%)	29	4.82352
	IGX	428(0.47%)	428.8(0.66%)	431(1.17%)	30	3.33216
Eil101	EPMX	668(6.2%)	684(8.74%)	701(11.45%)	110	10.7484
	GSX2	671(6.68%)	682.9(8.57%)	698(10.97%)	96	5.37888
	UHX	637(1.27%)	649.7(3.29%)	664(5.56%)	43	15.1632
	VGX	631(0.32%)	641.1(1.92%)	653(3.82%)	43	14.39256
	DPX	642(2.07%)	653.3(3.86%)	670(6.52%)	29	4.77516
	PBX	670(6.52%)	675.7(7.42%)	687(9.22%)	34	16.44864
	IGX	634(0.79%)	640.5(1.83%)	652(3.66%)	54	10.94496
kroA10	EPMX	22295(4.76%)	22959.6(7.88%)	24013(12.83%)	119	11.80764
0	GSX2	21940(3.09%)	22492.5(5.69%)	23068(8.39%)	105	5.91396
	UHX	21320(0.18%)	21440.4(0.74%)	21573(1.37%)	42	15.21156
	VGX	21320(0.18%)	21491.8(0.99%)	21706(1.99%)	45	15.08676
	DPX	21393(0.52%)	21743.8(2.17%)	23181(8.92%)	34	5.031
	PBX	22603(6.21%)	22915.3(7.67%)	23392(9.91%)	28	13.33332
	IGX	21292(0.05%)	21510.7(1.07%)	21794(2.41%)	43	9.00588
kroA20	EPMX	32347(10.14%)	33264.8(13.27%)	34297(16.78%)	262	43.46472
0	GSX2	31378(6.84%)	32437.8(10.45%)	33440(13.87%)	243	23.37192
	UHX	29680(1.06%)	29950.6(1.98%)	30872(5.12%)	81	56.73096
	VGX	29706(1.15%)	29995.6(2.14%)	30392(3.49%)	57	38.35104
	DPX	30079(2.42%)	30532.2(3.96%)	31077(5.82%)	47	15.57192
	PBX	30996(5.54%)	32285.7(9.93%)	33679(14.68%)	26	41.68788
	IGX	29649(0.96%)	29773.3(1.38%)	29870(1.71%)	43	17.03832
A280	EPMX	2887(11.94%)	3081(19.46%)	3169(22.88%)	380	79.69104
	GSX2	2923(13.34%)	3002.5(16.42%)	3066(18.88%)	364	44.57076
	UHX	2649(2.71%)	2693.9(4.46%)	2766(7.25%)	80	62.65116
	VGX	2639(2.33%)	2662.4(3.23%)	2683(4.03%)	69	61.1598
	DPX	2651(2.79%)	2720.4(5.48%)	2776(7.64%)	49	24.33756
	PBX	2841(10.16%)	2882.2(11.76%)	2925(13.42%)	40	115.60848
	IGX	2593(0.54%)	2625.1(1.79%)	2654(2.91%)	57	28.3842
Lin318	EPMX	46956(11.72%)	48373.9(15.1%)	50058(19.1%)	465	112.4214
	GSX2	45971(9.38%)	47307.6(12.56%)	48573(15.57%)	440	62.4078
	UHX	43354(3.15%)	44003.7(4.7%)	45078(7.25%)	126	137.82756
	VGX	43293(3.01%)	43756.6(4.11%)	44327(5.47%)	78	81.6816
	DPX	44381(5.6%)	45052.9(7.19%)	45814(9.01%)	68	40.86732
	PBX	46940(11.68%)	47843.6(13.83%)	48479(15.35%)	31	106.0176
	IGX	42992(2.29%)	43486.1(3.47%)	44031(4.76%)	75	44.93424

Table 1 Experimental results







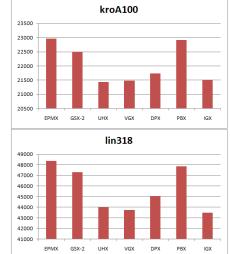


Figure 4. Average length

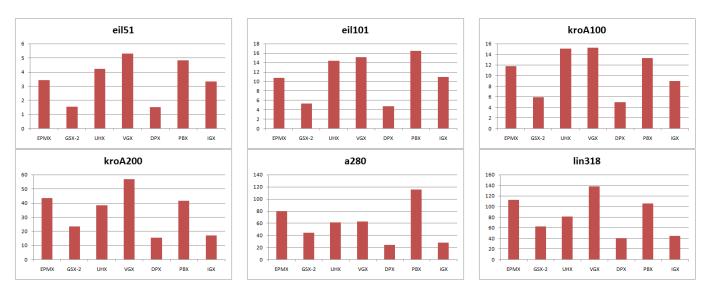


Figure 5. Average time of GA convergence when uses each of crossovers.

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